

NON-PROVISIONAL PATENT APPLICATION

TITLE: RETRIEVAL AND CONNECTION SYSTEM FOR A DISCONNECTABLE MOORING YOKE

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BACKGROUND OF THE INVENTION

Cross Reference to Related Application

This non-provisional application claims priority from provisional application 60/425,804 filed on November 12, 2002.

5 Field of the Invention

This invention relates generally to Floating Production Storage and Offloading vessels (FPSOs) including those for LNG liquefaction, production, and storage. In particular, this invention relates to tandem offloading of a permanently moored LNG liquefaction and storage vessel.

10 Description of Prior Art

Periodically LNG carrier vessels arrive at a FPSO, with Liquified Natural Gas stored therein and load the liquefied gas for transport to distant ports. Highly reliable and safe temporary mooring equipment is required to mechanically connect the LNG carrier to the stern of the FPSO in offshore sea conditions while Liquified Natural Gas transfer occurs 15 between the two vessels. The offshore energy industry requires apparatus to safely pull the LNG carrier vessel into position for mooring and to draw the yoke tip of the FPSO and the LNG carrier bow extension together and into controlled contact and mechanical connection and safe disconnection of the vessels.

Identification of Objects of the Invention

The primary objects of this invention are to:

- a. Provide an arrangement for a yoke retrieval system that safely pulls the LNG carrier bow into proximity with the yoke tip of the FPSO with minimal assistance from auxiliary handling vessels during moderate sea states of about 3.5 meters significant wave height with cross winds and currents;
- b. Provide an apparatus that lifts the floating yoke tip out of the water and guides the yoke tip into connecting position within the LNG carrier bow extension while large fluctuating pull-in chain loads occur with chain angles up to about 30 degrees from a horizontal plane;
- c. Provide an apparatus that provides for frequent and reliable connection and disconnection of the yoke from the LNG carrier; and
- d. Provide a connection device that provides quick emergency disconnection of the yoke from the LNG carrier.

SUMMARY OF THE INVENTION

The objects identified above are incorporated in a mooring yoke and method of mooring a vessel to a body such as an LNG process vessel by connecting the yoke to the vessel. The yoke is pivoted at its broad end to the LNG process vessel. The tip of the yoke has a buoyant element so that the tip end of the yoke floats on the sea prior to mooring operations. A windlass is provided, on the mooring yoke itself or on the LNG process vessel, that pulls a chain or rope connected to a bow extension of the LNG carrier or shuttle vessel, thereby pulling the vessel and yoke toward each other. Ultimately, force pulling the chain or rope lifts the yoke tip and a self-aligning guide cone from the sea and upward into contact with a receiver for a mechanical connection.

BRIEF DESCRIPTION OF THE DRAWINGS

The various objects and advantages of this invention will become apparent to those skilled in the art upon an understanding of the following detailed description of the invention, read in light of the accompanying drawings which are made a part of this specification and in
5 which::

Figure 1A is a plan view of a FPSO vessel and a yoke moored LNG carrier;

Figure 1 B is a side elevation view of the FPSO vessel and yoke moored LNG carrier;

Figure 2A is a plan view of the yoke of Figure 1A and 1B;

Figure 2B is a side elevation view of the yoke of Figure 2A;

10 Figure 3 is an elevation view partially in section through the yoke tip;

Figures 4, 5, 6, 7, 8, 9, 10 illustrate sequence steps for connecting the LNG carrier to the FPSO;

Figures 11, 12, and 13 illustrate sequence steps for disconnecting an LNG carrier from a FPSO;

15 Figure 14 illustrates an alternative arrangement of the yoke tip;

Figure 15 is an elevation view of an alternative yoke mooring arrangement with a windlass mounted on the LNG/FPSO vessel pulling a rope for connecting the LNG to the FPSO;

20 Figures 16A and 16B respectively illustrate details of the mating receiver on the bow extension of the LNG carrier vessel and a mating cone and yoke tip with a pull-in line passing through a U-joint of the mating cone;

Figure 16C is a partially cut-away perspective view of the mating cone of the yoke tip locked to a connector which illustrates connection of the mating cone to a three-axis gimbaled joint and connection of the mating cone to a hydraulic connector on an extension of
25 the vessel;

Figure 17 illustrates the yoke tip as it is being pulled into the receiver as the windlass on the LNG/FPSO vessel pulls on the retrieval rope with the mating cone entering the receiver on the bow extension; and

Figure 18 illustrates the yoke tip locked in the receiver.

5 **DESCRIPTION OF PREFERRED EMBODIMENTS OF THE INVENTION**

The preferred embodiments of the invention illustrated by reference to the drawings as indicated above, includes reference numbers to the various parts and elements. A summary of the names assigned to those parts and elements follows.

- | | | |
|----|----------|-----------------------------|
| | 1 | FPSO vessel |
| 10 | 2 | LNG carrier vessel (LNGC) |
| | 3 | Workboat |
| | 4 | LNG transfer system |
| | 5 | Support frame |
| | 6 | Piping pantograph |
| 15 | 8 | Bow extension |
| | 9 | Control room |
| | 10 | Disconnectable mooring yoke |
| | 11a, 11b | Mooring Winch |
| | 12a, 12b | Hawser |
| 20 | 13 | Floating rope |
| | 14a, 14b | Hinge joint |
| | 15 | Yoke tip |
| | 16 | Yoke frame |
| | 17 | Messenger rope |
| 25 | 18 | Chain windlass |
| | 19 | End fitting |
| | 20 | Retrieval chain |
| | 21 | Chain pocket wheel |
| | 22 | Chain guide wheel |
| 30 | 23 | Electrical power cable |
| | 24 | Chain locker |

	26a, 26b	Chain guide wheel
28		Buoyant chamber
30		Three-axis flexible joint
32		Guide cone
5	32"	Guide cone extension
	33	Radius
	34	Receiver
	35	Pedestal
	36	Elastomeric bumper
10	37	Connector in unlocked position
	38	Connector in locked position
	40	Pull-in rope
	41	Rope sheave
	42	Stopper
15	44	Shock absorber
	46	Connector control panel
	48	Winch
	50	Service platform
	52	Platform trolley
20	80	Dogs
	82	Grooves
	90	Two-axis gimbaled joint
	92	Outer profile of guide cone extension
	100	Rope winch
25	100'	Rope winch
	106	Winch drum
	110	Rope
	114	Fixed rope sheave
	120	Elastomeric spring
30	130	Moveable rope sheave
	134	Sheave frame
	136	Support bracket

Figures 1A and 1B illustrate FPSO vessel 1 with LNG carrier 2 connected in tandem by means of disconnectable mooring yoke 10. LNG transfer system 4 provides a transfer arrangement for transferring liquefied natural gas (LNG) from either vessel to the other. FPSO vessel 1 is one of several types of process vessels including a liquefaction process or a
5 gas to liquids process. LNG transfer system 4 is shown as one application for this invention. The arrangements described herein are applicable to other mooring systems where it is necessary to connect a mooring yoke to a floating vessel in environmental conditions of sea states of about 3.5 meters significant wave height with cross winds and currents.

Figures 2A and 2B show one embodiment of the invention of disconnectable mooring
10 yoke 10 including hinge joints 14a and 14b, yoke frame 16, buoyant chamber 28, chain windlass 18, and guide cone 32 mounted on yoke 16 by a three-axis flexible joint 30. Chain 20 can be run out of, or retrieved into, chain locker 24 by rotationally powered chain pocket wheel 21. Chain guide wheel 22 maintains sufficient wrap of chain 20 around pocket wheel 21. Chain guide wheels 26a and 26b maintain chain 20 alignment around and upward
15 through guide cone 32. The preferred connection of the yoke 10 to the LNG/FPSO 1 is described in provisional application 60/401,478 filed on August 6, 2002, now U.S. Application 10/636,994 filed on August 6, 2003 which is incorporated herein by reference. The frame 5 of the FPSO 1 to which the pantograph connection 4 is mounted is described in
provisional application 60/408,274 filed on September 6, 2002, also now U.S. Application
20 10/636,994 filed on August 6, 2003, which is also incorporated herein by reference.

Figure 3 illustrates a first embodiment of the invention with major components of the yoke tip 15 and bow extension 8. Guide cone 32 is flexibly and rotationally mounted on pedestal 35 of yoke tip 15 by means of three axis joint 30. Three-axis joint 30 is fabricated as a spherical ball joint, or a gimbaled cardan joint with a central third axis bearing, or an
25 elastomeric flexible joint combined with a central third axis bearing, or the like. Elastomeric

bumpers 36 are mounted on pedestal 35 and provide a cushioned stop for guide cone 32 at its extreme deflection angle. Chain 20 is fastened to LNG carrier bow extension 8 by means of chain end fitting 19 which is clamped by chain stopper 42 and supported by shock absorber 44. Shock absorber 44 is an elastomeric, spring-like element that minimizes shock loads in 5 chain 20 while guide cone 32 is pulled toward receiver 34. An alternative of shock absorber 44 is to incorporate the elastomeric element into chain guide wheel 26b shown in Figure 2B. In this alternative design, wheel 26b is mounted for example in a hinged bracket fastened at one end to shock absorber 44 so chain tension loads compress absorber 44. A more detailed description by reference to Figures 14A, 14B is presented below. Guide cone 32 is free to 10 enter or be released from receiver 34 when a connector is in an unlocked position 37 as shown in Figure 3. Guide cone 32 is held rigidly in receiver 34 by dogs 80 forced into grooves 82 when the connector is in the locked position 38. Operational control of the connector illustrated in positions 37 and 38 is performed at connector control station 46, or from a remote control station (not shown).

15 Figures 4 through Figure 10 inclusive describe generally the method of connecting an approaching LNG carrier vessel 2 to a FPSO process vessel 1. The major sequential steps in the procedure begin as shown in Figure 4A in which workboat 3 tows hawsers 12a, 12b from winches 11a, 11b out to LNG carrier vessel 2. Hawsers 12a, 12b are retrieved onto vessel 2 and secured as shown in Figure 5A.

20 Vessel 2 is pulled closer to FPSO vessel 1 by turning winches 11a, 11b to pull in hawsers 12a, 12b. Chain windlass 18 has paid out a length of chain 20 below yoke 10 in preparation for retrieval of chain pull-in rope 40 onto vessel 2. Skilled personnel in control room 9 operate chain windlass 18. The embodiment shown in Figures 1 through 14 locate windlass 18 directly on yoke 10 and the windlass includes a hydraulic pump unit and oil 25 reservoir contained within yoke frame structure 16 of yoke 10 driven by electrical current

through power cables 23 from vessel 1. Messenger rope 17 is prepared for subsequent connection to floating rope 13 to enable retrieval of pull-in rope 40 into receiver 34.

Figure 5B shows messenger rope 17 connected to pull-in rope 40 after vessel 2 crewmen have removed floating rope 13. Rope 17 and rope 40 are pulled toward vessel 2 by 5 winch 48 on vessel 2 shown in Figure 3.

Figure 6A shows yoke 10 floating in the sea due to the buoyancy of chamber or tank 28. Chain 20 is now connected to rope 40 with chain end fitting 19 secured in hydraulically operated chain stopper 42. Again refer to Figure 3.

Figure 6B illustrates chain 20 now being pulled through guide cone 32 by windlass 10 18, thereby drawing vessel 2 and mooring yoke 10 closer together, assisted by tension in hawsers 12a,12b from winch 11a,11b.

Figures 7A and 7B show vessel 2 moored by hawsers 12a, 12b, held by winches 11a, 11b, operated from control room 9 while windlass 18 pulls in more chain 20. Buoyant chamber 28 is being lifted from the sea, as chain 20 is pulled tighter. Wave action against 15 yoke buoyant chamber 28 causes shock loads in chain 20 that react against elastic shock absorber 44 shown in Figure 3.

Figure 8A illustrates guide cone 32 in contact with receiver 34. Cone 32 is self aligning and endures impact loading by transmitting and absorbing impact energy through absorber 44 and elastomeric bumper 36.

20 Figure 8B shows guide cone 32 almost fully engaged into receiver 34.

Figure 9A shows yoke 10 fully mooring vessel 2 to vessel 1 with guide cone 32 locked into receiver 34 by connector 38. (See Figure 3)

Figure 9B illustrates vessel 2 moored to vessel 1 and with piping pantograph 6 being pulled down for connection to vessel 2.

Figure 10 shows the connection completed with vessel 2 moored to vessel 1 and an LNG transfer system 4 in the operational configuration.

Figure 11A shows a typical operating condition just prior to completion of product transfer through transfer system 4 wherein vessel 2 is offset in the aft direction due to wind 5 and wave forces. Vessel 2 could also be applying a reverse thrust with its main propeller.

Figure 11B shows transfer system 4 disconnected and piping pantograph 6 folding upward away from vessel 2 while vessel 2 remains securely moored to vessel 1 by yoke 10.

Figure 12A illustrates yoke 10 being lowered into the sea following release of connector 38 from engagement with guide cone 32 (See Figure 3). A disconnection under 10 normal circumstances such as relatively mild weather conditions can be done by releasing connector 38 while chain 20 remains engaged by end fitting 19 in chain stopper 42 (again refer to Figure 3). Windlass 18 then pays out chain thereby lowering guide cone 32 away from receiver 34 until buoyant chamber 28 rests in the sea. At that point stopper 42 hydraulically releases chain 20, and chain 42 is lowered away by winch 48 by paying out 15 rope 40. An alternative quick release can be performed, such as in an emergency, by releasing stopper 42 from chain end fitting 19, then releasing connector 38, thereby allowing guide cone 32 to rapidly drop away from receiver 34.

Figure 12B shows vessel 2 backing away from vessel 1 following disconnection from yoke 10 that is now floating in the sea.

20 Figure 13A illustrates yoke 10 being prepared for lifting clear of the sea for parking or service purposes during long periods while awaiting a carrier vessel to arrive. Service platform 50 is moved over piping pantograph 5 by trolley 52. Chain 20 is then connected to service platform 50, or alternatively, directly to support frame 5.

Figure 13B shows yoke 10 raised up to a maximum height while suspended by chain 25 20 connected to platform 50, or alternatively connected to frame 5. Although not shown in

Figure 13B, additional snubbing lines would be connected from vessel 1 to yoke 10 to prevent undesirable motions while suspended above the sea. Another embodiment for suspending the yoke includes additional wire rope cables (not shown), one or more, attached to auxiliary winches (not shown) mounted on support frame 5 and connecting to support points at the yoke tip. The auxiliary winches mounted on frame 5 are arranged to lift yoke tip 15 up out of the sea.

Figures 14A and Figure 14B illustrate an alternative arrangement of equipment for pulling yoke 10 and vessel 2 together and for ultimately engaging cone 32 into receiver 34 (again refer to Figure 3). The arrangement of Figures 14A and 14B provides an alternative to utilizing chain 20 as described in the previous embodiments. Shock absorber 44, shown in Figure 3, is not be used, and instead elastomeric spring 120 is installed in yoke tip 15 to serve the same purpose of absorbing shock loads in rope 110 during yoke pull-in. The advantage of this embodiment is that it is characterized by lighter total yoke weight and lower manufacturing cost.

Rope 110 is preferably a high strength synthetic fiber rope such as Marlow Steelite™ lightweight fiber rope manufactured using Dyneema® HMPE fiber. The yoke retrieval operations sequence is essentially the same for this embodiment as was previously described for using retrieval chain 20. The retrieval process begins with floating rope 13 being retrieved onto vessel 2 as described above and shown in Figure 5A and Figure 5B. Winch 100 rotationally releases drum 106 to allow rope 110 to be freely pulled toward vessel 2 by means of rope 40 being wound onto winch 48 on bow extension 8 of vessel 2. Floating rope 13 and rope 40 are each made to a practical length of about 20 meters or longer. After end fitting 19 travels into stopper 42, winch 100 can begin pulling in rope 110. Rope 110 travels down through a central opening in guide cone 32, through joint 30, around vertically moveable sheave 130, around fixed sheave 114, and then to winch drum 106. Shock loads

occurring in rope 110 cause moveable sheave 130 and sheave frame 134 to be lifted upward thereby compressing elastomeric spring 120.

Spring 120 is a commercially available component typically used for dock bumpers for berthing ships. Compression of spring 120 absorbs large quantities of energy, thereby
5 greatly reducing the peak loads in rope 110. Spring 120 is firmly attached to support bracket 136 to transmit rope 110 loads into yoke structure 16.

Figures 15 through 18 illustrates another embodiment of the invention where a rope winch 100' is positioned not on the yoke itself, but on the stern of the vessel 1 in the vicinity of winch 11a but near the centerline of vessel 1. The tension member 110 in this embodiment
10 is a high strength synthetic fiber rope as described above, and is wound around rope sheaves 140, 142 and 144 and is terminated in an end fitting 19' as shown in Figure 16B. Figure 16A illustrates the receiver 34' carried by extension or connection module 8. A hydraulic connector 42' is secured on connection module 8 to selectively capture end fitting 19' when it is pulled upward by messenger line 40' similar to the illustration of Figures 2B and 3. Figure
15 16C illustrates, in a cross-section cut away elevation drawing, the mating cone 32' locked in the connector 42' after it has been fully pulled in and locked. The mating cone 32' is carried on a two-axis gimbaled joint 90 with an internal vertical axis yaw bearing which allows the cone 32' and cone extension member 32" to rotate about a vertical axis through a center line through pedestal 35. An elastomeric flex joint can be substituted for the two-axis gimbaled
20 joint. Such a flex joint can be a universal type (Hooke's joint) or a tapered stress joint of metallic or composite construction, or a flex joint using metallic or composite materials. Cone extension member 32" is sized for allow rope 110 to pass through its center (see Figure 16B) and has an outer profile 92 arranged with grooves so that locking members or dogs 80 of connector 42 can lock yoke tip 15' to receiver 34'.

Figure 17 shows the rope fitting 19' locked in connector 42' with the yoke tip 15' being pulled up into receiver 34' because of pulling on rope 110 by winch 100' (Figure 15). During this phase of the connection, the cone extension member 32" bears against rope 110 to tilt cone 32' to guide the cone 32' with receiver 34'. Figure 18 shows the mating cone 32'
5 locked into receiver 34' with hydraulic dogs 80 closed onto grooves on the outer profile 90 of cone extension member 32".